

Type	L#	Hit	Search Text	DBs	Time Stamp	Comments	Error Definition	Error Type
8	BRS	L8 17	(test\$3 or evaluation) and joints and (force adj1 sensor) and ((angle or angular\$3) with sensor) and shoulder and elbow and wrist	USP AT; US- PGP EPO	2003/07/12 19:26		0	

u →	Documen t ID	Issue Date	Pa ge s	Title	Curren t OR	Curren t XRef	Retri eval Class	Inventor	s	c	p	2	3
1	<input type="checkbox"/> <input checked="" type="checkbox"/> US 6564888 B1	20030 520	20	Biped mobile robot	180/8. 6	901/1		Gomi, Hirosi et al.	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>